

Inoculation Strategies for Victims of Viruses

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Outline

- 1 The Model
 - The Basic Problem
 - Game Theoretic Model
- 2 Nash Equilibrium
 - Characterization
 - Computing pure Nash Equilibrium
- 3 Optimizing Social Cost
 - Characterization
 - Sum of Squares Partition Problem

Meet the Authors...



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The Basic Problem

- Consider System of networked computers
- If a virus infects some node it eventually infects all the unprotected neighbors of infected machine
- Best strategy to install antivirus software on all machines?
- Each machine owner decides to install antivirus software or decides to get infected.

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The Model

- Players: n players corresponding to nodes in the graph
- Strategies: A node i has two possible strategies- to inoculate or to get infected denoted by a_i . Nodes strategy profile is denoted by $\vec{a} \in [0, 1]^n$.
- Attack Graph: let nodes that choose to install software be $I_{\vec{a}}$. Now attack graph is $G - I_{\vec{a}}$
- Given the choices of the nodes, virus chooses a node uniformly randomly to infect. Now virus infects the unprotected nodes and all its neighbours.

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Attack Graph

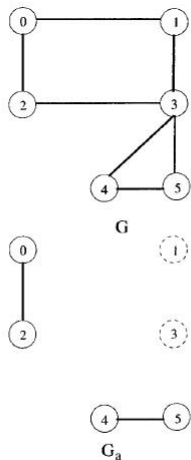


Figure 1: Sample graph G and its attack graph G_a for $\vec{a} = 010100$.

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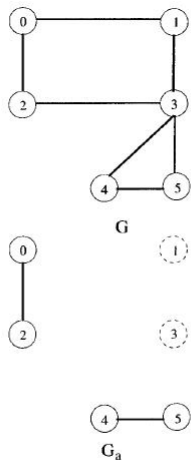


Figure 1: Sample graph G and its attack graph G_a for $\vec{a} = 010100$.

The Model

- Cost Model: Let C be the cost of antivirus software and L be the cost due to virus infection. Then given a strategy profile $\vec{a} \in [0, 1]^n$, the cost to node i is -

$$\text{cost}_i(\vec{a}) = a_i C + (1 - a_i) L \cdot p_i(\vec{a})$$

Where $p_i(\vec{a})$ is the probability that node i gets infected *given that it chooses to get infected*, and $p_i(\vec{a}) = k_i/n$, Where k_i is the size of the connected component in which node i is present.

- Social cost: Given a strategy profile $\vec{a} \in [0, 1]^n$, total social cost is given by -

$$\text{cost}(\vec{a}) = \sum_{j=0}^{n-1} \text{cost}_j(\vec{a})$$

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Mixed Equilibria

Theorem

Let $S(i)$ be the expected size of the insecure component that contains node i of the attack graph $G_{\vec{a}[i/0]}$ and let $t = Cn/L$ then a strategy profile \vec{a} is a Nash equilibrium if and only if

- 1) $\forall i$ such that $a_i = 1$, $S(i) \geq t$
- 2) $\forall i$ such that $a_i = 0$, $S(i) \leq t$
- 3) $\forall i$ such that $0 < a_i < 1$, $S(i) = t$

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Pure Equilibria

Theorem

Let $t = Cn/L$ then a strategy profile \vec{a} is a pure Nash equilibrium if and only if

- 1) Every component in the attack graph $G_{\vec{a}}$ has size at most t*
- 2) Inserting any secure node $j \in I_{\vec{a}}$ and its edges into $G_{\vec{a}}$ yields a component of size at least t .*

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Constructive proof of Existence

Theorem

Starting From any pure strategy profile \vec{a} , if at each step some participant with a suboptimal strategy switches its strategy, the system converges to pure Nash Equilibrium in no more than $2n$ steps.

Proof.

Define a potential function as -

$$\Phi(\vec{a}) = \sum_{A \in S_{big}(\vec{a})} |A| - \sum_{A \in S_{small}(\vec{a})} |A|$$



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Extremal Nash Equilibria

Theorem

Computing the pure Nash equilibrium with lowest cost and highest cost are NP – hard problems

Proof.

For lowest cost reduce *Vertex Cover* to decision problem *Does there exist Nash Equilibrium with cost less than c ?*

For highest cost reduce *Independent Dominating Set* to decision problem *Does there exist Nash Equilibrium with cost greater than c ?...* □

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Characterization and NP-hardness

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If \vec{a} is an optimum strategy, then every component in attack graph $G_{\vec{a}}$ has size at most $\max(1, (t+1)/2)$

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It is NP-hard to compute a socially optimal strategy

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Reduction to sum of squares

Reduction

The Optimization can be restated as, find the set of nodes I_a to secure such that the objective function-

$$C |I_a| + \frac{L}{n} \sum_{V \in \phi(I_a)} |V|^2$$

is minimized. Now assume that we know the value of $|I_a|$ that optimizes this function then the problem reduces minimizing the second term.

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Sum of Squares Partition

Sum of Squares Partition Problem

By removing a set F of at most m nodes, partition the graph into disconnected components H_1, H_2, \dots, H_k such that $\sum_i |H_i|^2$ is minimum.

Theorem

Let OPT be the optimum objective function value for the sum-of-squares partition problem on G with removal of at most m nodes, then we can find a set of $O(\log^2 n)m$ nodes, such that their removal creates disconnected components H_1, H_2, \dots, H_k such that $\sum_i |H_i|^2 \leq O(1) \cdot OPT$.

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Extensions and Open Issues

- Friendship Nash Equilibrium¹ and existence of pure Nash Equilibria in presence of friendship factor
- To reach the Nash Equilibrium each node needs to know the structure of complete graph. How to model this problem so that reaching NE does not require the knowledge of complete graph.
- Consider a model in which players have to report to the central enforcer who their neighbors are...
- Better Approximation algorithm for the sum of squares partition problem.

¹On Windfall of Friendship : Inoculation Strategies on Social Network, Stefan Schmid et. al. in EC 2008

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For Further Reading

-  On Windfall of Friendship : Inoculation Strategies on Social Networks , Stefan Schmid et al. Electronic Commerce 2008.
-  When Selfish meets Evil: Byzantine Players in Virus Inoculation Game, Stefan Schmid et al. PODC 2006
-  Inoculation Strategies for victims of viruses and sum of squares partition problem, James Aspnes et al. Technical Report , Yale University July 2004

Friendship Nash Equilibrium

A potential function

What about Potential Function

$$\Phi(\vec{a}) = \sum_{i=1}^k (\alpha_i - \beta_i)$$

Where , $k = \#$ of components in $G_{\vec{a}}$

$\alpha_i = \#$ of nodes in component i for whom the component is too large,

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